
Bias Reduced Peaks over Threshold Tail Estimation

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2 Abstract:

3 • Bias reduction in tail estimation has mainly been performed in case of Pareto-type models; see for
4 instance Drees (1996), Peng (1998), Feuerverger and Hall (1999), Beirlant et al. (1999, 2002), Gomes
5 and Martins (2002) and Caeiro et al. (2005, 2009). In that context, Beirlant et al. (2009) and
6 Papastathopoulos and Tawn (2013) constructed distributional models that are based on second order
7 rates of convergence for distributions of peaks over thresholds (POT). Such approach also allows to
8 connect the tail and the bulk of the distribution.

9 Bias reduction for all max-domains of attractions, i.e. without restricting to the Pareto-type case,
10 received much less attention up to now. Here we extend the second-order refined POT approach
11 started in Beirlant et al. (2009) providing a bias reduction technique for the classical generalized
12 Pareto (GP) approximation for POTs. We consider parametric and nonparametric modelling of the
13 second order component.

14 Key-Words:

15 • *Peaks over Threshold; Generalized Pareto distribution; Tail estimation; Mixture models.*

16 AMS Subject Classification:

17 • 62G32, 62F10, 62F15, 62J07.

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1. INTRODUCTION

1 Extreme value (EV) methodology starts from the assumption that the distribution of the avail-
 2 able sample X_1, X_2, \dots, X_n belongs to the domain of attraction of a generalized extreme value
 3 distribution, i.e. there exists sequences $(b_n)_n$ and $(a_n > 0)_n$ such that as $n \rightarrow \infty$

$$(1.1) \quad \frac{\max(X_1, X_2, \dots, X_n) - b_n}{a_n} \rightarrow_d Y_\xi,$$

4 where $\mathbb{P}(Y_\xi \leq y) = \exp(-(1 + \xi y)^{-1/\xi})$, for some $\xi \in \mathbb{R}$ with $1 + \xi y > 0$. The parameter ξ is
 5 termed the extreme value index (EVI). It is well-known (see e.g. Beirlant et al., 2004, and de
 6 Haan and Ferreira, 2006) that (1.1) is equivalent to the existence of a positive function $t \mapsto \sigma_t$,
 7 such that

$$(1.2) \quad \mathbb{P}\left(\frac{X-t}{\sigma_t} > y | X > t\right) = \frac{\bar{F}(t + y\sigma_t)}{\bar{F}(t)} \rightarrow_{t \rightarrow x_+} \bar{H}_\xi^{GP}(y) = (1 + \xi y)^{-1/\xi},$$

8 where $\bar{F}(x) = \mathbb{P}(X > x)$ and x_+ denotes the endpoint of the distribution of X . The conditional
 9 distribution of $X - t$ given $X > t$ is called the peaks over threshold (POT) distribution, while
 10 \bar{H}_ξ^{GP} is the survival function of the generalized Pareto distribution (GPD).
 11

12 Estimation of ξ and tail quantities such as return periods is then based on fitting a GPD
 13 to the observed excesses $X - t$ given $X > t$. The main difficulty in such an EV application
 14 is the choice of the threshold t . Most often, the threshold t is chosen as one of the top data
 15 points $X_{n-k,n}$ for some $k \in \{1, 2, \dots, n\}$ where $X_{1,n} \leq X_{2,n} \leq \dots \leq X_{n,n}$ denotes the ordered
 16 sample. The parameters (ξ, σ) are then estimated by fitting the GPD $H_\xi^{GP}(\frac{y}{\sigma})$ to the spacings
 17 $X_{n,n} - X_{n-k,n}, \dots, X_{n-k+1,n} - X_{n-k,n}$.
 18

19 The limit result in (1.2) requires t to be chosen as large as possible (or, equivalently, k as
 20 small as possible) for the bias in the estimation of ξ and other tail parameters to be limited.
 21 However, in order to limit the estimation variance, t should be as small as possible, i.e. the
 22 number of data points k used in the estimation should be as large as possible. Several adaptive
 23 procedures for choosing t or k have been proposed, but mainly in the Pareto-type case with
 24 $\xi > 0$, i.e. when

$$(1.3) \quad \bar{F}(x) = x^{-1/\xi} \ell(x),$$

25 for some slowly varying function ℓ , i.e. satisfying $\frac{\ell(yt)}{\ell(t)} \rightarrow 1$ as $t \rightarrow \infty$, for every $y > 1$. One then
 26 typically assumes a second-order specification of (1.3) of the type

$$(1.4) \quad \frac{\ell(yt)}{\ell(t)} - 1 = \delta_t \left(y^{-\beta} - 1 \right),$$

27 where $\delta_t = \delta(t) = t^{-\beta} \tilde{\ell}(t)$, with $\beta > 0$ and $\tilde{\ell}$ slowly varying at infinity.
 28

29 As an alternative, bias reduction techniques have been proposed in the Pareto-type case
 30 $\xi > 0$, among others in Feuerverger and Hall (1999), Beirlant et al. (1999, 2002) and Gomes and

1 Martins (2002). However while the bias is reduced, the variance is increased. In Caeiro et al.
 2 (2005, 2009) methods are proposed to limit the variance of bias-reduced estimators assuming a
 3 third-order slow variation model. These methods focus on the distribution of the log-spacings
 4 of high order statistics. Other construction methods for asymptotically unbiased estimators of
 5 $\xi > 0$ were introduced in Peng (1998) and Drees (1996).
 6 Another approach consists of proposing penultimate limit distributions. In case $\xi > 0$, Beirlant
 7 et al. (2009) proposed an extension of the Pareto distribution (EPD) to approximate the tail
 8 probability of the POT distribution $\mathbb{P}\left(\frac{X}{t} > y | X > t\right)$ as $t \rightarrow \infty$:

$$(1.5) \quad \bar{H}_{\xi, \delta, \rho}^{EP}(y) = 1 - H_{\xi, \delta, \rho}^{EP}(y) = y^{-1/\xi} \left(1 + \delta_t \left((y^{-1/\xi})^{-\rho} - 1\right)\right), \quad y > 1,$$

9 with δ_t satisfying $\delta_t \downarrow 0$ as $t \rightarrow \infty$ and $\rho = -\beta\xi$. In the literature, the second order parameter ρ
 10 typically is estimated externally with a different sequence of extreme order statistics than with
 11 ξ and δ , or it is given an appropriate 'canonical' value such as -1. We suppress the notation ρ
 12 from the extended distribution notation.

Fitting the extended Pareto distribution $H_{\xi, \sigma}^{EP}$ to the relative excesses $\left\{\frac{X_{n-j+1, n}}{X_{n-k, n}}, j = 1, \dots, k\right\}$ leads to estimates of ξ that are more stable as a function of k compared to the original ML estimator derived by Hill (1975)

$$\hat{\xi}_{k, n}^H = \frac{1}{k} \sum_{j=1}^k \log \frac{X_{n-j+1, n}}{X_{n-k, n}},$$

13 which is obtained by fitting the Pareto distribution $H_{\xi, 0}^{EP}$. Denoting the maximum likelihood
 14 estimators of ξ by $\hat{\xi}_k^{EP}$, it can indeed be shown under the assumption that the EP model for the
 15 excesses X/t is correct and that ρ is estimated consistently, that the asymptotic bias of $\hat{\xi}_k^{EP}$ is
 16 0 as long as $k(k/n)^{-2\rho} \rightarrow \lambda \geq 0$ as $k, n \rightarrow \infty$, while the asymptotic bias of $\hat{\xi}_{k, n}^H$ is only 0 when
 17 $k(k/n)^{-2\rho} \rightarrow 0$. On the other hand, the asymptotic variance of $\hat{\xi}_k^{EP}$ equals $\left(\frac{1-\rho}{\rho}\right)^2 \frac{\xi^2}{k}$, where $\frac{\xi^2}{k}$
 18 is the asymptotic variance of $\hat{\xi}_{k, n}^H$.

19

20 In case of a real-valued EVI, for the selection of an appropriate threshold or the construc-
 21 tion of bias-reduced methods, only a few methods are available. Dupuis (1999) suggested a
 22 robust model validation mechanism to guide the threshold selection, assigning weights between
 23 0 and 1 to each data point where a high weight means that the point should be retained since a
 24 GPD model is fitting it well. However, thresholding is required at the level of the weights and
 25 hence the method cannot be used in an unsupervised manner. Buitendag et al. (2019) present a
 26 ridge regression method to reduce the bias of the generalized Hill estimator proposed in Beirlant
 27 et al. (2005).

28

29 In this paper we concentrate on bias reduction when fitting the GPD to the distribution
 30 of POTs $X - t | X > t$ using maximum likelihood estimation. We hence extend the second-order
 31 refined POT approach based on $\bar{H}_{\xi, \delta}^{EP}$ from (1.5) to all max-domains of attraction. Here the
 32 corresponding basic second order regular variation theory can be found in Theorem 2.3.8 in de
 33 Haan and Ferreira (2006) stating that

$$(1.6) \quad \lim_{t \rightarrow x_+} \frac{\mathbb{P}(X - t > y\sigma_t | X > t) - (1 + \xi y)^{-1/\xi}}{\delta(t)} = (1 + \xi y)^{-1-1/\xi} \Psi_{\xi, \bar{\rho}}((1 + \xi y)^{1/\xi}),$$

1 with $\delta(t) \rightarrow 0$ as $t \rightarrow x_+$ and $\Psi_{\xi, \tilde{\rho}}(x) = \frac{1}{\tilde{\rho}} \left(\frac{x^{\xi+\tilde{\rho}}-1}{\xi+\tilde{\rho}} - \frac{x^{\xi}-1}{\xi} \right)$ which for the cases $\xi = 0$ and $\tilde{\rho} = 0$
 2 is understood to be equal to the limit as $\xi \rightarrow 0$ and $\tilde{\rho} \rightarrow 0$. We further allow more flexible
 3 second-order models than the ones arising from second-order regular variation theory such as in
 4 (1.6) using non-parametric modelling of the second-order component and the flexible semipara-
 5 metric GP modelling introduced in Tencaliec et al. (2019). This newly proposed method can
 6 also be applied to the specific case of Pareto-type distributions.

7

8 In the next section we propose our extended GPD models, and detail the estimation
 9 methods. Some basic asymptotic results are provided in section 3. In the final section we
 10 discuss simulation results and some practical case studies.

2. TRANSFORMED AND EXTENDED GPD MODELS

11 In this paper we propose to approximate the POT distribution with an extended GPD model
 12 with survival function

$$(\mathcal{E}) : \quad \bar{F}_t^{EGP}(y) = \bar{H}_\xi^{GP}\left(\frac{y}{\sigma}\right) \left\{ 1 + \delta_t B_\eta \left(\bar{H}_\xi^{GP}\left(\frac{y}{\sigma}\right) \right) \right\},$$

13 where

- 14 • $\delta_t = \delta(t) \rightarrow 0$ as $t \rightarrow x_+$,
- 15 • $B_\eta(1) = 0$ and $\lim_{u \rightarrow 0} u^{1-\epsilon} B_\eta(u) = 0$ for every $0 < \epsilon < 1$,
- 16 • B_η is twice continuously differentiable.

17 Here the parameter η represents a second order nuisance parameter. For negative δ -values one
 18 needs $\delta_t > \left\{ \min_u \left(1 - \frac{d}{du} (u B_\eta(u)) \right) \right\}^{-1}$ to obtain a valid distribution.

19 Note that this model is a transformation model $G_t \left(\bar{H}_\xi^{GP}\left(\frac{y}{\sigma}\right) \right)$ where the transformation func-
 20 tion $G_t : (0, 1) \rightarrow (0, 1)$, $u \mapsto u(1 + \delta_t B_\eta(u))$ satisfies $\frac{G_t(u)}{u} \rightarrow 1$ as $t \rightarrow \infty$ for every $u \in (0, 1)$ as
 21 follows from (1.2).

22 Also, model (\mathcal{E}) generalizes the EPD model (1.5) replacing the Pareto survival function $y^{-1/\xi}$
 23 ($\xi > 0$) by the GPD survival function \bar{H}_ξ^{GP} ($\xi \in \mathbb{R}$), and considering a general function $B_\eta(u)$.

24

25 We here detail a *parametric and non-parametric estimation procedure* for (ξ, σ) under (\mathcal{E}) based
 26 on excesses $Y_{j,k} = X_{n-j+1,n} - X_{n-k,n}$ ($j = 1, \dots, k$), while considering external estimation of the
 27 parameters in the B_η component of the model. In this we use the reparametrization (ξ, τ) with
 28 $\tau = \xi/\sigma$. Modelling the distribution of the exceedances Y with model (\mathcal{E}) leads to maximum

1 likelihood estimators based on the excesses $Y_{j,k} = X_{n-j+1,n} - X_{n-k,n}$ ($j = 1, \dots, k$):

$$(2.1) \quad (\hat{\xi}_k^E, \hat{\tau}_k^E, \hat{\delta}_k^E) = \operatorname{argmax} \left\{ \sum_{j=1}^k \log \left(1 + \delta_k b_\eta \left((1 + \tau Y_{j,k})^{-1/\xi} \right) \right. \right. \\ \left. \left. + \sum_{j=1}^k \log \left\{ \frac{\tau}{\xi} (1 + \tau Y_{j,k})^{-1-1/\xi} \right\} \right\}$$

2 with $b_\eta(u) = \frac{d}{du}(uB_\eta(u))$ for a given choice of B_η .

3 Estimates of small tail probabilities $\mathbb{P}(X > c)$ are then obtained through

$$\hat{\mathbb{P}}_k^E(X > c) = \frac{k}{n} \bar{H}_{\hat{\xi}_k^E}^{GP} \left(\frac{\hat{\tau}_k^E}{\hat{\xi}_k^E} (c - X_{n-k,n}) \right) \left(1 + \hat{\delta}_k^E \hat{B}_\eta \left(\bar{H}_{\hat{\xi}_k^E}^{GP} \left(\frac{\hat{\tau}_k^E}{\hat{\xi}_k^E} (c - X_{n-k,n}) \right) \right) \right).$$

4 A general approach to choose the parameters contained in the B_η component can be to minimize
5 the variance of the obtained estimates of ξ over $k = 2, \dots, n$. See also the simulation section 4.

6 **A parametric approach** (Ep). The second-order result (1.6) leads to the parametric choice

7 $B_{\xi, \tilde{\rho}}(u) = \frac{u^\xi}{\tilde{\rho}} \left(\frac{u^{-\xi-\tilde{\rho}-1}}{\xi+\tilde{\rho}} - \frac{u^{-\xi-1}}{\xi} \right)$ in case $\xi + \tilde{\rho} \neq 0$ and $\xi \neq 0$.

8 Model (\mathcal{E}) allows for bias reduction in the estimation of (ξ, τ) under the assumption that the
9 corresponding second-order model (1.6) is correct for the POTs $X - t | X > t$. Note that here
10 the B_η component contains two parameters ξ and $\tilde{\rho}$. So in this component ξ and $\tilde{\rho}$ will be
11 substituted with an external value.

12 Here

$$b_\eta(u) = u^{-\tilde{\rho}} \left(\frac{1 - \tilde{\rho}}{\tilde{\rho}(\xi + \tilde{\rho})} \right) + u^\xi \left(\frac{1 + \xi}{\xi(\xi + \tilde{\rho})} \right) - \frac{1}{\xi\tilde{\rho}},$$

13 in which the classical estimator of ξ (with $\delta_k = 0$), or an appropriate value ξ_0 , is used to substi-
14 tute ξ . A consistent estimator of $\tilde{\rho}$ is provided in Fraga Alves et al. (2003). Another option is to
15 choose $(\xi_0, \tilde{\rho})$ minimizing the variance in the plot of the resulting estimates of ξ as a function of k .

16

17 **A non-parametric approach** ($E\tilde{p}$). In practice a particular distribution probably follows laws
18 of nature, environment or business and does not have to follow the second-order regular variation
19 assumptions as in (1.6). A non-parametric approximation of $u \mapsto uB_\eta(u)$ can be obtained from
20 an estimator \hat{G}_{t_*} of G_{t_*} , or equivalently \hat{G}_{k_*} of G_{k_*} , of the transformation $G_t(u) = u(1 + \delta_t B_\eta(u))$
21 ($u \in (0, 1)$) at some particular t_* or k_* . Indeed, using $\hat{G}_{k_*}^{(m)}(u) - u$ as an approximation of
22 $u \mapsto \delta_{k_*} u B_\eta(u)$, and reparametrizing δ_k by δ_k / δ_{k_*} , we obtain $\hat{b}_{\eta, k_*}(u) = -1 + \frac{d}{du} \hat{G}_{k_*}^{(m)}(u)$ as an
23 estimator of b_η .

24

25 For any t , an estimator \hat{G}_t of G_t can be obtained using the Bernstein polynomial algorithm from
26 Tencaliec et al. (2019). The Bernstein approximation of order m of a continuous distribution
27 function G on $[0, 1]$ is given by

$$G^{(m)}(u) = \sum_{j=0}^m G \left(\frac{j}{m} \right) \binom{m}{j} u^j (1-u)^{m-j}, \quad u \in [0, 1].$$

1 As in Babu et al. (2002) one then replaces the unknown distribution function G itself with the
 2 empirical distribution function \hat{G}_n of the available data in order to obtain a smooth estimator
 3 of G :

$$\hat{G}_n^{(m)}(u) = \sum_{j=0}^m \hat{G}_n \left(\frac{j}{m} \right) \binom{m}{j} u^j (1-u)^{m-j}.$$

4 Note that G_t is the distribution function of $\bar{H}_\xi^{GP}(Y/\sigma)$. Hence, in the present application, data
 5 from G_t are only available after imputing a value for (ξ, τ) . This then leads to the iterative
 6 algorithm from Tencaliec et al. (2019), which is applied to every threshold t , or every number
 7 of top k data.

8 (i) Set starting values $(\hat{\xi}_k^{(0)}, \hat{\tau}_k^{(0)})$. Here one can use $(\hat{\xi}_k^{ML}, \hat{\tau}_k^{ML})$ from using $G_t(u) = u$.
 9 (ii) Iterate for $r = 0, 1, \dots$ until the difference in loglikelihood taken in $(\hat{\xi}_k^{(r)}, \hat{\tau}_k^{(r)})$ and $(\hat{\xi}_k^{(r+1)}, \hat{\tau}_k^{(r+1)})$
 10 is smaller than a prescribed small value:

11 (a) Given $(\hat{\xi}_k^{(r)}, \hat{\tau}_k^{(r)})$ construct rv's $\hat{Z}_{j,k} = \left(1 + \hat{\tau}_k^{(r)} Y_{j,k}\right)^{-1/\hat{\xi}_k^{(r)}}$
 12 (b) Construct Bernstein approximation based on $\hat{Z}_{j,k}$ ($1 \leq j \leq k$)

$$\hat{G}_k^{(m)}(u) = \sum_{j=0}^m \hat{G}_k \left(\frac{j}{m} \right) \binom{m}{j} u^j (1-u)^{m-j}$$

13 with \hat{G}_k the empirical distribution function of $\hat{Z}_{j,k}$

14 (c) Obtain new estimates $(\hat{\xi}_k^{(r+1)}, \hat{\tau}_k^{(r+1)})$ with ML:

$$\begin{aligned} (\hat{\xi}_k^{(r+1)}, \hat{\tau}_k^{(r+1)}) = \operatorname{argmax} \left\{ \sum_{j=1}^k \log \{ \hat{g}_k^{(m)}((1 + \tau \hat{Z}_{j,k})^{-1/\xi}) \} \right. \\ \left. + \sum_{j=1}^k \log \left\{ \frac{\tau}{\xi} (1 + \tau \hat{Z}_{j,k})^{-1-1/\xi} \right\} \right\} \end{aligned}$$

15 with $\hat{g}_k^{(m)}$ denoting the derivative of $\hat{G}_k^{(m)}$.

16 As noted in Tencaliec et al. (2019) a theoretical study of these estimates is difficult and has not
 17 been established.

18
 19 **Remark 1.** The estimation methods described above of course can be rewritten for the specific
 20 case of Pareto-type distributions where the distribution of POTs $Y = \frac{X}{t} | X > t$ are approximated
 21 by transformed Pareto distributions. The model (\mathcal{E}) is then rephrased as

$$(\mathcal{E}^+) : \quad \bar{F}_t^E(y) = \bar{H}_\xi^P(y) \{1 + \delta_t B_\eta(\bar{H}_\xi^P(y))\}.$$

22 The likelihood estimation method, now based on the exceedances $Y_{j,k} = X_{n-j+1,n}/X_{n-k,n}$ ($j =$
 23 $1, \dots, k$), is then adapted to

$$(2.2) \quad (\hat{\xi}_k^{E+}, \hat{\delta}_k^{E+}) = \operatorname{argmax} \left\{ \sum_{j=1}^k \log \left(1 + \delta_k b_\eta(Y_{j,k}^{-1/\xi}) \right) + \sum_{j=1}^k \log \left\{ \frac{1}{\xi} (Y_{j,k})^{-1-1/\xi} \right\} \right\}.$$

- 1 Note that the (Ep^+) approach using the parametric version $B_\eta(u) = u^{-\rho} - 1$ for a particular
 2 fixed $\rho < 0$ equals the EPD method from Beirlant et al. (2009), while $(E\bar{p}^+)$ is new.
- 3 Estimators of tail probabilities are then given by

$$\hat{\mathbb{P}}_k^{E+}(X > c) = \frac{k}{n} \bar{H}_{\hat{\xi}_k^{E+}}^P(c/X_{n-k,n}) \left(1 + \hat{\delta}_k^{E+} \hat{B}_\eta \left(\bar{H}_{\hat{\xi}_k^{E+}}^P(c/X_{n-k,n}) \right) \right).$$

3. BASIC ASYMPTOTICS UNDER MODEL (\mathcal{E})

- 4 In this section we discuss the asymptotic properties of the maximum likelihood estimators
 5 solving (2.1) and (2.2). To this end, as in Beirlant et al. (2009), we develop the likelihood
 6 equations up to linear terms in δ_k since $\delta_k \rightarrow 0$ with decreasing value of k . Below we set
 7 $\bar{H}_\theta(y) = (1 + \tau y)^{-1/\xi}$ when using extended GPD modelling, while $\bar{H}_\theta(y) = y^{-1/\xi}$ when using
 8 extended Pareto modelling under $\xi > 0$.

- 9 *Extended Pareto POT modelling.* The likelihood problem (2.2) was already considered in Beir-
 10 lant et al. (2009) in case of parametric modelling for B_η . We here propose a more general
 11 treatment. The limit statements in the derivation can be obtained using the methods from Beir-
 12 lant et al. (2009). Denoting the log-likelihood function in (2.2) by ℓ , the likelihood equations
 13 are given by

$$(3.1) \quad \begin{cases} \frac{\partial}{\partial \xi} \ell = -\frac{k}{\xi} + \frac{1}{\xi^2} \sum_{j=1}^k \log Y_{j,k} + \frac{\delta_k}{\xi^2} \sum_{j=1}^k \frac{b'_\eta(\bar{H}_\theta(Y_{j,k})) \bar{H}_\theta(Y_{j,k}) \log Y_{j,k}}{1 + \delta_k b_\eta(\bar{H}_\theta(Y_{j,k}))} \\ \frac{\partial}{\partial \delta_k} \ell = \sum_{j=1}^k b_\eta(\bar{H}_\theta(Y_{j,k})) - \delta_k \sum_{j=1}^k b_\eta^2(\bar{H}_\theta(Y_{j,k})). \end{cases}$$

- 14 *Extended Generalized Pareto POT modelling.* The likelihood equations following from (2.1) up
 15 to linear terms in δ_k are now given by

$$\begin{cases} \frac{\partial}{\partial \xi} \ell = -\frac{k}{\xi} + \frac{1}{\xi^2} \sum_{j=1}^k \log(1 + \tau Y_{j,k}) + \frac{\delta_k}{\xi^2} \sum_{j=1}^k b'_\eta(\bar{H}_\theta(Y_{j,k})) \bar{H}_\theta(Y_{j,k}) \log(1 + \tau Y_{j,k}) \\ \frac{\partial}{\partial \tau} \ell = \frac{k}{\xi \tau} \left\{ -1 + (1 + \xi) \frac{1}{k} \sum_{j=1}^k \frac{1}{1 + \tau Y_{j,k}} \right. \\ \quad \left. - \frac{\delta_k}{k} \sum_{j=1}^k b'_\eta(\bar{H}_\theta(Y_{j,k})) (\tau Y_{j,k}) (1 + \tau Y_{j,k})^{-1-1/\xi} \right\} \\ \frac{\partial}{\partial \delta_k} \ell = \sum_{j=1}^k b_\eta(\bar{H}_\theta(Y_{j,k})) - \delta_k \sum_{j=1}^k b_\eta^2(\bar{H}_\theta(Y_{j,k})), \end{cases}$$

- 16 from which

$$(3.2) \quad \begin{cases} \hat{\delta}_k = \frac{\sum_{j=1}^k b_\eta(\bar{H}_{\hat{\theta}_k}(Y_{j,k}))}{\sum_{j=1}^k b_\eta^2(\bar{H}_{\hat{\theta}_k}(Y_{j,k}))}, \\ \frac{1}{k} \sum_{j=1}^k \log(1 + \hat{\tau}_k Y_{j,k}) = \hat{\xi}_k - \frac{\hat{\delta}_k}{k} \sum_{j=1}^k b'_\eta(\bar{H}_{\hat{\theta}_k}(Y_{j,k})) \bar{H}_{\hat{\theta}_k}(Y_{j,k}) \log(1 + \hat{\tau}_k Y_{j,k}), \\ \frac{1}{k} \sum_{j=1}^k \frac{1}{1 + \hat{\tau}_k Y_{j,k}} = \frac{1}{1 + \hat{\xi}_k} + \frac{\hat{\delta}_k}{1 + \hat{\xi}_k} \left\{ \frac{1}{k} \sum_{j=1}^k b'_\eta(\bar{H}_{\hat{\theta}_k}(Y_{j,k})) \bar{H}_{\hat{\theta}_k}(Y_{j,k}) \right. \\ \quad \left. - \frac{1}{k} \sum_{j=1}^k b'_\eta(\bar{H}_{\hat{\theta}_k}(Y_{j,k})) \bar{H}_{\hat{\theta}_k}(Y_{j,k}) \frac{1}{1 + \hat{\tau}_k Y_{j,k}} \right\}. \end{cases}$$

- 17 Under the extended model we now state the asymptotic distribution of the estimators $(\hat{\xi}_k^E, \hat{\tau}_k^E)$
 18 and $\hat{\xi}_k^{E+}$. To this end let Q denote the quantile function of F , and let $U(x) = Q(1 - x^{-1})$ denote

1 the corresponding tail quantile function. Model (\mathcal{E}) assumption can be rephrased in terms of U :

$$(\tilde{\mathcal{E}}) : \frac{\frac{U(vx)-U(v)}{\sigma_{U(v)}} - h_\xi(x)}{\delta(U(v))} \xrightarrow{v \rightarrow \infty} x^\xi B_\eta(1/x),$$

2 where $h_\xi(x) = (x^\xi - 1)/\xi$ and $\delta(U)$ regularly varying with index $\tilde{\rho} < 0$. Moreover in the mathe-
3 matical derivations one needs the extra condition that for every $\epsilon, \nu > 0$, and v, vx sufficiently
4 large

$$(\tilde{\mathcal{E}}_2) : \left| \frac{\frac{U(vx)-U(v)}{\sigma_{U(v)}} - h_\xi(x)}{\delta(U(v))} - x^\xi B_\eta(1/x) \right| \leq \epsilon x^\xi |B_\eta(1/x)| \max\{x^\nu, x^{-\nu}\}.$$

5 Similarly, (\mathcal{E}^+) is rewritten as

$$(\tilde{\mathcal{E}}^+) : \frac{\frac{U(vx)}{U(v)} - x^\xi}{\xi \delta(U(v))} \xrightarrow{v \rightarrow \infty} x^\xi B_\eta(1/x).$$

6 The analogue of $(\tilde{\mathcal{E}}_2)$ in this specific case is given by

$$(\tilde{\mathcal{E}}_2^+) : \left| \frac{\frac{U(vx)}{U(v)} - x^\xi}{\xi \delta(U(v))} - x^\xi B_\eta(1/x) \right| \leq \epsilon x^\xi |B_\eta(1/x)| \max\{x^\nu, x^{-\nu}\},$$

7 with $\delta(U)$ regularly varying with index $\rho < 0$.

8 Finally, in the expression of the asymptotic variances we use

$$Eb_\eta^2 = \int_0^1 b_\eta^2(u) du, \quad EB_\eta = \int_0^1 B_\eta(u) du, \quad EC_\eta = \int_0^1 u^\xi B_\eta(u) du.$$

9 The proof of the next theorem is outlined in the Appendix. It allows to construct confidence
10 intervals for the estimators of ξ obtained under the extended models.

11 **Theorem 1** Let $k = k_n$ be a sequence such that $k, n \rightarrow \infty$ and $k/n \rightarrow 0$ such that $\sqrt{k}\delta(U(n/k)) \rightarrow$
12 $\lambda \in \mathbb{R}$. Moreover assume that in (2.1) and (2.2), B_η is substituted by a consistent estimator as
13 $n \rightarrow \infty$. Then

i. when $\xi > -1/2$ with $(\tilde{\mathcal{E}}_2)$

$$\left(\sqrt{k}(\hat{\xi}_k^E - \xi), \sqrt{k}\left(\frac{\hat{\tau}_k^E}{\tau} - 1\right) \right) \rightarrow_d \mathcal{N}_2(\mathbf{0}, \Sigma)$$

$$\Sigma = \frac{\xi^2}{D} \begin{pmatrix} \frac{1}{(1+\xi)^2(1+2\xi)} - \frac{(EC_\eta)^2}{Eb_\eta^2} & \frac{1}{\xi(1+\xi)^3} - \frac{EB_\eta EC_\eta}{\xi(1+\xi)Eb_\eta^2} \\ \frac{1}{\xi(1+\xi)^3} - \frac{EB_\eta EC_\eta}{\xi(1+\xi)Eb_\eta^2} & \frac{1}{\xi^2(1+\xi)^2} \left(1 - \frac{(EB_\eta)^2}{Eb_\eta^2}\right) \end{pmatrix}$$

15 where

$$D = \left(\frac{1}{(1+\xi)^2(1+2\xi)} - \frac{(EC_\eta)^2}{Eb_\eta^2} \right) \left(1 - \frac{(EB_\eta)^2}{Eb_\eta^2} \right) - \left(\frac{1}{(1+\xi)^2} - \frac{EB_\eta EC_\eta}{Eb_\eta^2} \right)^2,$$

ii. when $\xi > 0$ with $(\tilde{\mathcal{E}}_2^+)$

$$\left(\sqrt{k}(\hat{\xi}_k^{E+} - \xi), \sqrt{k}(\hat{\delta}_k^{E+} - \delta_k) \right) \rightarrow_d \mathcal{N}_2(\mathbf{0}, \Sigma^+),$$

$$\Sigma^+ = \frac{1}{Eb_\eta^2 - (EB_\eta)^2} \begin{pmatrix} \xi^2 Eb_\eta^2 & -\xi EB_\eta \\ -\xi EB_\eta & 1 \end{pmatrix}$$

- 1 **Remark 2.** The asymptotic variance of $\hat{\xi}_k^{E+}$ is larger than the asymptotic variance ξ^2 of the
 2 Hill estimator $\hat{\xi}_{k,n}^H$. Indeed,

$$\begin{aligned} (EB_\eta)^2 &= \left(\int_0^1 \log(1/u) b_\eta(u) du \right)^2 \\ &= \left(\int_0^1 (\log(1/u) - 1) b_\eta(u) du \right)^2 \\ &\leq \left(\int_0^1 (\log(1/u) - 1)^2 du \right) \left(\int_0^1 b_\eta^2(u) du \right) \\ &= (Eb_\eta^2), \end{aligned}$$

- 3 where the above inequality follows using the Cauchy-Schwarz inequality.
 4 Similarly, one can show that

$$(EC_\eta)^2 = \xi^{-2} \left(\int_0^1 \left(u^\xi - \frac{1}{1+\xi} \right) b_\eta du \right)^2 \leq \frac{1}{(1+2\xi)(1+\xi)^2} (Eb_\eta^2).$$

- 5 The asymptotic variance of $\hat{\xi}_k^E$ equals

$$\frac{(1+\xi)^2}{k} \frac{1 - (1+\xi)^2(1+2\xi)(EC_\eta)^2 / (Eb_\eta^2)}{1 - \frac{(1+\xi)^4(1+2\xi)}{\xi^2} (Eb_\eta^2)^{-1} [(EC_\eta)^2 - 2 \frac{(EC_\eta)(EB_\eta)}{(1+\xi)^2} + \frac{(EB_\eta)^2}{(1+\xi)^2(1+2\xi)}]}$$

- 6 which can be shown to be larger than the asymptotic variance $(1+\xi)^2/k$ of the classical GPD
 7 maximum likelihood estimator. In the parametric case with $B_\eta(u) = \frac{u^\xi}{\tilde{\rho}} \left(\frac{u^{-\xi-\tilde{\rho}}-1}{\xi+\tilde{\rho}} - \frac{u^{-\xi}-1}{\xi} \right)$,
 8 one obtains $EB_\eta = (1+\xi)^{-1}(1-\tilde{\rho})^{-1}$, $EC_\eta = (1+\xi)^{-1}(1+2\xi)^{-1}(\xi-\tilde{\rho}+1)^{-1}$ and $Eb_\eta^2 =$
 9 $2(1+2\xi)^{-1}(1-2\tilde{\rho})^{-1}(\xi-\tilde{\rho}+1)^{-1}$. It then follows that the asymptotic variance of $\hat{\xi}_k^E$ equals
 10 $\frac{(1+\xi)^2}{k} \left(\frac{1-\tilde{\rho}}{\tilde{\rho}} \right)^2$.

- 11 In case $\xi > 0$ with $B_\eta(u) = u^{-\rho} - 1$, the asymptotic variance of $\hat{\xi}_k^{E+}$ is given by $\frac{\xi^2}{k} \left(\frac{1-\rho}{\rho} \right)^2$ as
 12 already found in Beirlant et al. (2009).

- 13 Finally, an asymptotic representation of $\sqrt{k}(\hat{\delta}_k^E - \delta_k)$ can be found at the end of the proof of
 14 Theorem 1 in the Appendix. \square

15

- 16 In the case studies in the next section asymptotic confidence intervals based on Theorem 1 can
 17 be added to the analysis.

18

- 19 **Remark 3.** Since in model (\mathcal{E}) the B_η factor is multiplied by δ_t , the asymptotic distribution of
 20 tail estimators based on (\mathcal{E}) will not depend on the asymptotic distribution of the estimator of
 21 B_η . As in Beirlant et al. (2009) when using the EPD model in the Pareto-type setting, one can
 22 rely in the parametric approach on consistent estimators of the nuisance parameter η using a
 23 larger proportion k_* of the data. Alternatively, one can also consider different values of η in the
 24 parametric approach, and of (k_*, m) in the non-parametric setting, and search for values of this
 25 nuisance parameter which stabilizes the plots of the EVI estimates as a function of k using the
 26 minimum variance principle for the estimates as a function of k . Clearly one loses the asymp-
 27 totic unbiasedness in Theorem 1 if B_η is not consistently estimated. For the moment no proof

1 is available to show that the estimators of the parameters in the second order component B_η
 2 through the minimum variance principle are consistent. Note that the estimator of $\tilde{\rho}$ presented
 3 in Fraga Alves et al. (2003) has been shown to be consistent.

4 As becomes clear from the simulation results, in many instances the extreme value index estima-
 5 tors are not very sensitive to such a misspecification, especially in the non-parametric approach
 6 leading to $E\bar{p}$ and $E\bar{p}^+$, and the proposed estimators can still outperform the classical maximum
 7 likelihood estimators based on the first order approximations of the POT distributions. \square

4. SIMULATIONS AND CASE STUDIES

8 Simulation results and practical cases are proposed in a Shinyapp written in R:

9 <https://phdshinygao.shinyapps.io/ExtendedModels/>

10 Under *Simulations* one finds simulation results with sample sizes $n = 200$ for different distribu-
 11 tions from each max-domain of attraction. The bias and MSE for the different estimators are
 12 plotted as a function of the number of exceedances k . Using the notation from the preceding
 13 sections one has a choice to apply the technique with \bar{H}_θ equal to the GPD, respectively the
 14 simple Pareto distribution (only when $\xi > 0$).

15

16 Sliders are provided for the following parameters:

- 17 • in case of GPD modelling: $\tilde{\rho}$ in Ep , and (k_*, m) in $E\bar{p}$ estimation,
- 18 • in case of Pareto modelling: ρ in Ep^+ , and (k_*, m) in $E\bar{p}^+$ estimation.

19 Again one can indicate to choose these parameters so as to minimize the variance of $\hat{\xi}_k$ over
 20 $k = 2, \dots, n$. The value of ξ in the parametric function $B_{\xi, \tilde{\rho}}$ in Ep is imputed with the classical
 21 GPD-ML estimator at the given value of k .

22 Also bias and RMSE plots of the corresponding tail probability estimates of $p = \mathbb{P}(X > c)$ are
 23 given, where c is chosen so that these probabilities equal $p = 0.005$ or $p = 0.003$. Here the bias,
 24 respectively RMSE, are expressed as the average, respectively the average of squared values, of
 25 $\log(p/\hat{p})$.

26 One can also change the vertical scale of the plots, smooth the figures by taking moving averages
 27 of a certain number of estimates. Finally one can download the figures in pdf.

28

29 While on the above link, several other distributions are used and sliders are provided for the
 30 different parameters ρ , $\tilde{\rho}$, and (k_*, m) , we collect here the resulting figures for estimation of
 31 ξ and estimating 0.003 tail probabilities, when using the minimum variance principle for all
 32 parameters, in case of the following subset of models:

- 33 • The Burr(τ, λ) distribution with $\bar{F}(x) = (1 + x^\tau)^{-\lambda}$ for $x > 0$ with $\tau = 1$ and $\lambda = 2$, so
 34 that $\xi = \frac{1}{\tau\lambda} = \frac{1}{2}$ and $\rho = \tilde{\rho} = -\frac{1}{\lambda} = -\frac{1}{2}$.

- 1 • The Fréchet(2) distribution with $\bar{F}(x) = 1 - \exp(-x^{-2})$ for $x > 0$, so that $\xi = \frac{1}{2}$ and
2 $\rho = \tilde{\rho} = -1$.
- 3 • The standard normal distribution with $\xi = 0$ and $\tilde{\rho} = 0$.
- 4 • The Exponential distribution with $\bar{F}(x) = e^{-\lambda x}$ for $x > 0$, so that $\xi = 0$ and $\tilde{\rho} = 0$.
- 5 • The Reversed Burr distribution with $\bar{F}(x) = (1 + (1-x)^{-\tau})^{-\lambda}$ for $x < 1$ with $\tau = 5$ and
6 $\lambda = 1$, so that $\xi = -1/(\tau\lambda) = -\frac{1}{5}$ with $\tilde{\rho} = -1/\lambda = -1$.
- 7 • The extreme value Weibull distribution with $\bar{F}(x) = 1 - e^{-(1-x)^\alpha}$ for $x < 1$ with $\alpha = 4$, so
8 that $\xi = -\frac{1}{4}$ with $\tilde{\rho} = -1$.

We also compare the bias and RMSE results for $\hat{\xi}_k^E$ with those of the ridge regression estimator presented in Buitendag et al. (2019). This regression method is constructed on the basis of a regression model of the type

$$Y_j = \xi + b_{n,k} \left(\frac{j}{k+1} \right)^{-\tilde{\rho}}, \quad j = 1, \dots, k,$$

where

$$Y_j = (j+1) \left(\log \frac{X_{n-j,n} \hat{\xi}_{j,n}^H}{X_{n-j-1,n} \hat{\xi}_{j+1,n}^H} - \log \left(1 + \frac{1}{j} \right) + \frac{1}{j} \right), \quad j = 1, \dots, n-1.$$

9 In case $\xi > 0$, the results for $\hat{\xi}_k^{E+}$ are also compared with the corrected Hill method presented
10 in Caeiro et al. (2005) and (2009), also based on regression representations of top order statis-
11 tics $X_{n-j+1,n}$, and which have been shown to have asymptotic bias 0 while keeping the same
12 asymptotic variance ξ^2/k as the Hill estimator $\hat{\xi}_{k,n}^H$ under a third-order slow variation model.
13

14 In general the minimum variance principle works well, though in some cases some improved
15 results can be obtained by choosing specific values of the parameters ρ , $\tilde{\rho}$, and (k_*, m) . This is
16 mainly the case for the Pareto-type models when using $E\bar{p}$, such as for the Fréchet distribution.
17 Also, in case of tail probability estimation using Ep for cases with $\xi < 0$ particular choices of
18 the corresponding parameters lead to improvements over the minimum variance principle.
19 Overall the Ep approach yields the best results, both in estimation of ξ and tail probabilities.
20 The improvement over the classical GPD maximum likelihood approach is smaller for $E\bar{p}$, and
21 in case of situations where the second order parameter $\tilde{\rho}$ equals 0 then $E\bar{p}$ basically equals the
22 ML estimators. Note that when $\tilde{\rho} = 0$ the conditions of the main theorem are not met, in which
23 case the GPD and the bias reductions are known to exhibit a large bias. This is typically the
24 case when $\xi = 0$. This is also known to be the case using simple Pareto modelling when $\rho = 0$.
25 The proposed methods compare well with the ridge regression method. One exception is the
26 Fréchet distribution (see Figure 3) in which the ridge regression method offers exceptionally
27 good results.
28

29 In case of simple Pareto modelling for $\xi > 0$ cases (see Figures 2 and 4) the Ep^+ and $E\bar{p}^+$ ap-
30 proaches yield serious improvements over the Hill estimator, with small bias for Ep^+ and $E\bar{p}^+$,
31 while the parametric approach Ep^+ naturally exhibits the best RMSE. The results obtained

with proposed methods are comparable with the CH estimator (see Figures 2 and 4).

Under *Applications* the app also offers the analysis of some case studies, some of which are discussed here in more detail. We use Belgian car insurance claim ultimates of a Belgian car insurance portfolio discussed in Albrecher et al. (2017), and lifetime data discussed in Einmahl et al. (2019). We then present estimates of ξ , σ and tail probabilities $\mathbb{P}(X > x_{n,n})$ with $x_{n,n}$ denoting the largest observation, so that the estimated probability is supposed to be close to $1/n$. An option is provided in the Shinyapp to construct asymptotic confidence intervals for ξ for the Ep and Ep^+ based estimates of ξ , on the basis of Theorem 1.

In actuarial statistics, Pareto-type modelling is customary in case of car insurance claim modelling. So here we provide both the plots of $\hat{\xi}_{k,n}^H$, Ep^+ , $E\bar{p}^+$ and the CH estimator (see top left in Figure 9), as well as the GPD-ML, Ep , $E\bar{p}$ and ridge regression estimator (bottom left in Figure 9), and the corresponding tail probability estimates at the right hand side. Under the Pareto approach, confining oneself to $\xi > 0$, the level 0.4 clearly appears for the EVI both using Ep^+ and $E\bar{p}^+$ when using the minimum variance principle. The CH estimator also shows a stable area around the value 0.5. The tail probability estimates of $\mathbb{P}(X > x_{n,n})$ are close to $1/n$ for almost all k values while the plot of the classical estimates is difficult to interpret.

With GPD based modelling two EVI levels are visible, around 0.2 and 0.4, of which the lower level is more clearly indicated when using $E\bar{p}$ with $k_* = 427$ and $m = 25$ as shown in Figure 9, bottom left. The ridge estimator is stable at the value 0.4. The corresponding tail probability estimates based on $E\bar{p}$ are also stable at the value $1/n$ for a long k range.

In Einmahl et al. (2019) the life spans are studied for Dutch males and females reaching age 92 years and higher, considering their age at death. For every year, from 1986 till 2015, the life spans of this subgroup were analyzed. The authors decided to use $k = 1500$ for every year when using the classical GPD-ML estimators, and found an EVI estimate $\hat{\xi}$ between -0.1 and -0.15 for females, while for males a value around -0.15 is common over the whole period. Here we restrict ourselves to the female data from 1986. The results of Ep with asymptotic confidence intervals as discussed in Remark 2 with $\bar{\rho} = -0.5$ are shown in Figure 10 (left). While the classical GPD-ML estimates decrease with increasing k from 1 to 1500, the Ep estimates show a more stable plot at a negative ξ value which is rather between -0.05 and -0.1. The ridge regression method shows a similar value for $k \leq 500$. The corresponding tail probability estimates for a larger k indicate a value closer to the tail probability estimate $1/n$ based on the empirical distribution function, in contrast to the classical GPD approach.

5. CONCLUSIONS

In this contribution we have constructed bias reduced estimators of tail parameters extending the classical POT method. The bias can be modelled parametrically (for instance based on second order regular variation theory), or non-parametrically using Bernstein polynomial approximations. A basic asymptotic limit theorem is provided for the estimators of the extreme value parameters which allows to compute asymptotic confidence intervals. A shinyapp has been

1 constructed with which the characteristics and the effectiveness of the proposed methods are
 2 illustrated through simulations and practical case studies. From this it follows that within the
 3 proposed methods it is always possible to improve upon the classical POT method both in bias
 4 and RMSE. This approach can also be used as a data analytic tool to enhance an extreme value
 5 analysis.

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7. Appendix

24 In this section we provide details concerning the proof of Theorem 1.

25

26 *Asymptotic distribution of $\hat{\xi}_k^{E+}$.*

27 From (3.1) we obtain up to linear terms in δ_k that (denoting $\hat{\xi}_k$ for $\hat{\xi}_k^{E+}$)

$$\begin{cases} \hat{\delta}_k = \frac{\sum_{j=1}^k b_\eta(Y_{j,k}^{-1/\hat{\xi}_k})}{\sum_{j=1}^k b_\eta^2(Y_{j,k}^{-1/\hat{\xi}_k})} \\ \hat{\xi}_k = \hat{\xi}_{k,n}^H + \hat{\delta}_k B_k^{(1)}, \end{cases}$$

28 with $B_k^{(1)} = \frac{1}{k} \sum_{j=1}^k b'_\eta(Y_{j,k}^{-1/\hat{\xi}_k}) Y_{j,k}^{-1/\hat{\xi}_k} \log Y_{j,k}$. As $k, n \rightarrow \infty$ and $k/n \rightarrow 0$ we have $B_k^{(1)} \rightarrow_p$
29 $-\xi \int_0^1 b'_\eta(u) u \log u du = -\xi EB_\eta$.

30 Using a Taylor expansion on the numerator of the right hand side of the first equation leads to

$$\frac{1}{k} \sum_{j=1}^k b_\eta(Y_{j,k}^{-1/\hat{\xi}_k}) = \frac{1}{k} \sum_{j=1}^k b_\eta(Y_{j,k}^{-1/\xi}) - (\hat{\xi}_k - \xi) \xi^{-1} (EB_\eta) (1 + o_p(1)),$$

1 so that, with $\frac{1}{k} \sum_{j=1}^k b_\eta^2(Y_{j,k}^{-1/\hat{\xi}_k}) \rightarrow_p Eb_\eta^2$, up to lower order terms

$$\hat{\delta}_k = \frac{1}{Eb_\eta^2} \frac{1}{k} \sum_{j=1}^k b_\eta(Y_{j,k}^{-1/\xi}) - (\hat{\xi}_k - \xi) \xi^{-1} \frac{EB_\eta}{Eb_\eta^2} (1 + o_p(1)).$$

2 Hence, inserting this expansion into $\hat{\xi}_k = \hat{\xi}_{k,n}^H + \hat{\delta}_k B_k^{(1)}$, finally leads to

$$\begin{aligned} \sqrt{k}(\hat{\xi}_k - \xi)(1 + o_p(1)) &= \frac{Eb_\eta^2}{Eb_\eta^2 - (EB_\eta)^2} \sqrt{k} (\hat{\xi}_{k,n}^H - \xi) - \frac{\xi EB_\eta}{Eb_\eta^2 - (EB_\eta)^2} \sqrt{k} \left(\frac{1}{k} \sum_{j=1}^k b_\eta(Y_{j,k}^{-1/\xi}) \right) \\ &= \frac{Eb_\eta^2}{Eb_\eta^2 - (EB_\eta)^2} \sqrt{k} (\hat{\xi}_{k,n}^H - \xi - \xi \delta_k EB_\eta) \\ &\quad - \frac{\xi EB_\eta}{Eb_\eta^2 - (EB_\eta)^2} \sqrt{k} \left(\frac{1}{k} \sum_{j=1}^k b_\eta(Y_{j,k}^{-1/\xi}) - \delta_k Eb_\eta^2 \right), \end{aligned}$$

3 with $\delta_k = \delta(U(n/k))$. We now show that this final expression is a linear combination of two zero
4 centered statistics (up to the required accuracy) which is asymptotically normal with the stated
5 asymptotic variance. To this end let $Z_{n-k,n} \leq Z_{n-k+1,n} \leq \dots \leq Z_{n,n}$ denote the top $k+1$ order
6 statistics of a sample of size n from the standard Pareto distribution with distribution function
7 $z \mapsto z^{-1}$, $z > 1$. Then from $(\tilde{\mathcal{E}}_2^+)$

$$\begin{aligned} \hat{\xi}_{k,n}^H &= \frac{1}{k} \sum_{j=1}^k (\log U(Z_{n-j+1,n}) - \log U(Z_{n-k,n})) \\ &= \frac{1}{k} \sum_{j=1}^k \log \left\{ \left(\frac{Z_{n-j+1,n}}{Z_{n-k,n}} \right)^\xi \left[1 + \xi \delta(U(Z_{n-k,n})) B_\eta \left(\frac{Z_{n-k,n}}{Z_{n-j+1,n}} \right) \right. \right. \\ &\quad \left. \left. + o_p(1) |\delta(U(Z_{n-k,n}))| B_\eta \left(\frac{Z_{n-k,n}}{Z_{n-j+1,n}} \right) \left| \left(\frac{Z_{n-j+1,n}}{Z_{n-k,n}} \right)^\epsilon \right| \right] \right\} \\ &= \xi \frac{1}{k} \sum_{j=1}^k \log \frac{Z_{n-j+1,n}}{Z_{n-k,n}} + \xi \delta(U(Z_{n-k,n})) \frac{1}{k} \sum_{j=1}^k B_\eta \left(\frac{Z_{n-k,n}}{Z_{n-j+1,n}} \right) \\ &\quad + o_p(1) |\delta(U(Z_{n-k,n}))| \frac{1}{k} \sum_{j=1}^k |B_\eta \left(\frac{Z_{n-k,n}}{Z_{n-j+1,n}} \right)| \left(\frac{Z_{n-j+1,n}}{Z_{n-k,n}} \right)^\epsilon. \end{aligned}$$

8 Now $\log Z_{n-j+1,n} - \log Z_{n-k,n} =_d E_{k-j+1,k}$, the $(k-j+1)$ th smallest value from a stan-
9 dard exponential sample E_1, \dots, E_k of size k , so that $\frac{1}{k} \sum_{j=1}^k \log \frac{Z_{n-j+1,n}}{Z_{n-k,n}} =_d \frac{1}{k} \sum_{j=1}^k E_j$ and
10 $\frac{1}{k} \sum_{j=1}^k B_\eta \left(\frac{Z_{n-k,n}}{Z_{n-j+1,n}} \right) =_d \frac{1}{k} \sum_{j=1}^k B_\eta(e^{-E_j}) =_d \frac{1}{k} \sum_{j=1}^k B_\eta(U_j)$ where U_1, \dots, U_k is a uniform
11 $(0,1)$ sample. Hence, since $\delta(U(Z_{n-k,n}))/\delta(U(n/k)) \rightarrow_p 1$ and $\frac{1}{k} \sum_{j=1}^k B_\eta(U_j) \rightarrow_p EB_\eta$, we have
12 that $\hat{\xi}_{k,n}^H - \xi - \xi \delta_k EB_\eta$ is asymptotically equivalent to $\frac{1}{k} \sum_{j=1}^k \xi(E_j - 1)$ as $\sqrt{k} \delta_k \rightarrow \lambda$.

1 Similarly

$$\begin{aligned}
\frac{1}{k} \sum_{j=1}^k b_\eta(Y_{j,k}^{-1/\xi}) &= \frac{1}{k} \sum_{j=1}^k b_\eta \left(\left[\frac{U \left(\frac{Z_{n-j+1,n}}{Z_{n-k,n}} Z_{n-k,n} \right)}{U(Z_{n-k,n})} \right]^{-1/\xi} \right) \\
&= \frac{1}{k} \sum_{j=1}^k b_\eta \left(\left(\frac{Z_{n-j+1,n}}{Z_{n-k,n}} \right)^{-1} \left[1 + \xi \delta(U(Z_{n-k,n})) B_\eta \left(\frac{Z_{n-k,n}}{Z_{n-j+1,n}} \right) \right. \right. \\
&\quad \left. \left. + o_p(1) |\delta(U(Z_{n-k,n}))| B_\eta \left(\frac{Z_{n-k,n}}{Z_{n-j+1,n}} \right) \left| \left(\frac{Z_{n-j+1,n}}{Z_{n-k,n}} \right)^\epsilon \right]^{-1/\xi} \right) \right) \\
&= \frac{1}{k} \sum_{j=1}^k b_\eta \left(\left(\frac{Z_{n-j+1,n}}{Z_{n-k,n}} \right)^{-1} \left[1 - \delta(U(Z_{n-k,n})) B_\eta \left(\frac{Z_{n-k,n}}{Z_{n-j+1,n}} \right) \right. \right. \\
&\quad \left. \left. + o_p(1) |\delta(U(Z_{n-k,n}))| B_\eta \left(\frac{Z_{n-k,n}}{Z_{n-j+1,n}} \right) \left| \left(\frac{Z_{n-j+1,n}}{Z_{n-k,n}} \right)^\epsilon \right] \right) \right) \\
&= \frac{1}{k} \sum_{j=1}^k b_\eta(e^{-E_j}) \\
&\quad - \delta(U(Z_{n-k,n})) \frac{1}{k} \sum_{j=1}^k b'_\eta \left(\frac{Z_{n-k,n}}{Z_{n-j+1,n}} \right) B_\eta \left(\frac{Z_{n-k,n}}{Z_{n-j+1,n}} \right) \left(\frac{Z_{n-k,n}}{Z_{n-j+1,n}} \right) (1 + o_p(1)).
\end{aligned}$$

2 Since $\delta(U(Z_{n-k,n}))/\delta_k \rightarrow_p 1$ and $\frac{1}{k} \sum_{j=1}^k b'_\eta \left(\frac{Z_{n-k,n}}{Z_{n-j+1,n}} \right) B_\eta \left(\frac{Z_{n-k,n}}{Z_{n-j+1,n}} \right) \left(\frac{Z_{n-k,n}}{Z_{n-j+1,n}} \right) \rightarrow_p -Eb_\eta^2$ it
3 follows that $\frac{1}{k} \sum_{j=1}^k b_\eta(Y_{j,k}^{-1/\xi}) - \delta_k Eb_\eta^2$ is asymptotically equivalent to $\frac{1}{k} \sum_{j=1}^k b_\eta(e^{-E_j}) =_d$
4 $\frac{1}{k} \sum_{j=1}^k b_\eta(U_j)$ as $\sqrt{k}\delta_k \rightarrow \lambda$, which is centered at 0 since $E(b_\eta(U)) = 0$. The results incor-
5 porating $\hat{\delta}_k^{E+}$ follow similarly.

6 *Asymptotic distribution of $\hat{\xi}_k^E$.*

7 This derivation follows similar lines starting from (3.2):

$$\begin{cases} \frac{1}{k} \sum_{j=1}^k b'_\eta(\bar{H}_{\hat{\theta}_k}(Y_{j,k})) \bar{H}_{\hat{\theta}_k}(Y_{j,k}) \log(1 + \hat{\tau}_k Y_{j,k}) \rightarrow_p -\xi EB_\eta, \\ \frac{1}{k} \sum_{j=1}^k b_\eta^2(\bar{H}_{\hat{\theta}_k}(Y_{j,k})) \rightarrow_p Eb_\eta^2, \\ \frac{1}{k} \sum_{j=1}^k b'_\eta(\bar{H}_{\hat{\theta}_k}(Y_{j,k})) \bar{H}_{\hat{\theta}_k}(Y_{j,k}) \rightarrow_p b_\eta(1), \\ \frac{1}{k} \sum_{j=1}^k b'_\eta(\bar{H}_{\hat{\theta}_k}(Y_{j,k})) \bar{H}_{\hat{\theta}_k}(Y_{j,k}) \frac{1}{1 + \hat{\tau}_k Y_{j,k}} \rightarrow_p \xi(1 + \xi) EC_\eta + b_\eta(1), \end{cases}$$

8 as $k, n \rightarrow \infty$ and $k/n \rightarrow \infty$, so that the system of equations is asymptotically equivalent to

$$\begin{cases} \hat{\delta}_k = \frac{\frac{1}{k} \sum_{j=1}^k b_\eta(\bar{H}_{\hat{\theta}_k}(Y_{j,k}))}{Eb_\eta^2}, \\ \frac{1}{k} \sum_{j=1}^k \log(1 + \hat{\tau}_k Y_{j,k}) = \hat{\xi}_k + \hat{\xi}_k \hat{\delta}_k EB_\eta \\ \frac{1}{k} \sum_{j=1}^k \frac{1}{1 + \hat{\tau}_k Y_{j,k}} = \frac{1}{1 + \hat{\xi}_k} - \hat{\xi}_k \hat{\delta}_k EC_\eta. \end{cases}$$

9 Using a Taylor expansion on the numerator of the right hand side of the first equation leads to

$$\hat{\delta}_k Eb_\eta^2 = \frac{1}{k} \sum_{j=1}^k b_\eta(\bar{H}_{\hat{\theta}_k}(Y_{j,k})) - \frac{EB_\eta}{\xi} (\hat{\xi}_k - \xi) + (1 + \xi) EC_\eta \left(\frac{\hat{\tau}_k}{\tau} - 1 \right).$$

- 1 Imputing this in the second and third equation in ξ and τ , and expanding these equations
- 2 linearly around the correct values (ξ, τ) , while using, as $k, n \rightarrow \infty$ and $k/n \rightarrow 0$

$$\frac{1}{k} \sum_{j=1}^k \frac{\tau Y_{j,k}}{1 + \tau Y_{j,k}} \rightarrow^p \frac{\xi}{1 + \xi} \quad \text{and} \quad \frac{1}{k} \sum_{j=1}^k \frac{\tau Y_{j,k}}{(1 + \tau Y_{j,k})^2} \rightarrow^p \frac{\xi}{(1 + \xi)(1 + 2\xi)},$$

- 3 leads to the linearized equations

$$(7.1) \quad \left\{ \begin{array}{l} \left(\hat{\xi}_k - \xi \right) \left(-1 + \frac{(EB_\eta)^2}{Eb_\eta^2} \right) + \left(\frac{\hat{\tau}_k}{\tau} - 1 \right) \left(\frac{\xi}{1+\xi} - \xi(1 + \xi) \frac{EB_\eta EC_\eta}{Eb_\eta^2} \right) \\ \quad = - \left(\frac{1}{k} \sum_{j=1}^k \log(1 + \tau Y_{j,k}) - \xi \right) + \frac{\xi EB_\eta}{Eb_\eta^2} \frac{1}{k} \sum_{j=1}^k b_\eta(\bar{H}_\theta(Y_{j,k})), \\ \left(\hat{\xi}_k - \xi \right) \left(\frac{1}{(1+\xi)^2} - \frac{EB_\eta EC_\eta}{Eb_\eta^2} \right) + \left(\frac{\hat{\tau}_k}{\tau} - 1 \right) \left(-\frac{\xi}{(1+\xi)(1+2\xi)} + \xi(1 + \xi) \frac{(EC_\eta)^2}{Eb_\eta^2} \right) \\ \quad = - \left(\frac{1}{k} \sum_{j=1}^k \frac{1}{1+\tau Y_{j,k}} - \frac{1}{1+\xi} \right) - \frac{\xi EC_\eta}{Eb_\eta^2} \frac{1}{k} \sum_{j=1}^k b_\eta(\bar{H}_\theta(Y_{j,k})). \end{array} \right.$$

Using similar derivations as in the case $\hat{\xi}_k^{E+}$, it follows that the right hand sides in (7.1) can be rewritten as a linear combination of two zero centered statistics from which the asymptotic normality of $(\sqrt{k}(\hat{\xi}_k^E - \xi), \sqrt{k}(\frac{\hat{\tau}_k^E}{\tau} - 1))$ can be obtained, as stated in Theorem 1:

$$\left\{ \begin{array}{l} \left(\hat{\xi}_k - \xi \right) \left(-1 + \frac{(EB_\eta)^2}{Eb_\eta^2} \right) + \left(\frac{\hat{\tau}_k}{\tau} - 1 \right) \left(\frac{\xi}{1+\xi} - \xi(1 + \xi) \frac{EB_\eta EC_\eta}{Eb_\eta^2} \right) \\ \quad = - \left(\frac{1}{k} \sum_{j=1}^k \log(1 + \tau Y_{j,k}) - \xi - \xi \delta_k EB_\eta \right) + \frac{\xi EB_\eta}{Eb_\eta^2} \left(\frac{1}{k} \sum_{j=1}^k b_\eta(\bar{H}_\theta(Y_{j,k})) - \delta_k Eb_\eta^2 \right), \\ \left(\hat{\xi}_k - \xi \right) \left(\frac{1}{(1+\xi)^2} - \frac{EB_\eta EC_\eta}{Eb_\eta^2} \right) + \left(\frac{\hat{\tau}_k}{\tau} - 1 \right) \left(-\frac{\xi}{(1+\xi)(1+2\xi)} + \xi(1 + \xi) \frac{(EC_\eta)^2}{Eb_\eta^2} \right) \\ \quad = - \left(\frac{1}{k} \sum_{j=1}^k \frac{1}{1+\tau Y_{j,k}} - \frac{1}{1+\xi} + \xi \delta_k EC_\eta \right) - \frac{\xi EC_\eta}{Eb_\eta^2} \left(\frac{1}{k} \sum_{j=1}^k b_\eta(\bar{H}_\theta(Y_{j,k})) - \delta_k Eb_\eta^2 \right). \end{array} \right.$$

We hence obtain the following asymptotic representation

$$\left(\hat{\xi}_k^E - \xi, \frac{\hat{\tau}_k^E}{\tau} - 1 \right)^t = W^{-1} \begin{pmatrix} -1 & 0 & \xi \frac{EB_\eta}{Eb_\eta^2} \\ 0 & -1 & -\xi \frac{EC_\eta}{Eb_\eta^2} \end{pmatrix} \left(U_k^{(1)}, U_k^{(2)}, U_k^{(3)} \right)^t$$

where

$$W = \begin{pmatrix} -1 + \frac{(EB_\eta)^2}{Eb_\eta^2} & \frac{\xi}{1+\xi} - \xi(1 + \xi) \frac{EB_\eta EC_\eta}{Eb_\eta^2} \\ \frac{1}{(1+\xi)^2} - \frac{EB_\eta EC_\eta}{Eb_\eta^2} & -\frac{\xi}{(1+\xi)(1+2\xi)} + \xi(1 + \xi) \frac{(EC_\eta)^2}{Eb_\eta^2} \end{pmatrix},$$

and

$$\sqrt{k} \left(U_k^{(1)}, U_k^{(2)}, U_k^{(3)} \right)^t := \begin{pmatrix} \frac{1}{k} \sum_{j=1}^k \log(1 + \tau Y_{j,k}) - \xi - \xi \delta_k EB_\eta \\ \frac{1}{k} \sum_{j=1}^k \frac{1}{1+\tau Y_{j,k}} - \frac{1}{1+\xi} + \xi \delta_k EC_\eta \\ \frac{1}{k} \sum_{j=1}^k b_\eta(\bar{H}_\theta(Y_{j,k})) - \delta_k Eb_\eta^2 \end{pmatrix}$$

is asymptotically normal with variance-covariance matrix

$$\Sigma_U = \begin{pmatrix} \xi^2 & -\xi^2(1 + \xi)^{-2} & \xi EB_\eta \\ -\xi^2(1 + \xi)^{-2} & \xi^2(1 + \xi)^{-2}(1 + 2\xi)^{-1} & -\xi EC_\eta \\ \xi EB_\eta & -\xi EC_\eta & Eb_\eta^2 \end{pmatrix}.$$

Concerning $\hat{\delta}_k^E$ we find the following representation:

$$(Eb_\eta^2)\sqrt{k} \left(\hat{\delta}_k^E - \delta_k \right) = \left((0 \ 0 \ 1) + (-EB_\eta/\xi \ (1 + \xi) EC_\eta) W^{-1} \begin{pmatrix} -1 & 0 & \xi \frac{EB_\eta}{Eb_\eta^2} \\ 0 & -1 & -\xi \frac{EC_\eta}{Eb_\eta^2} \end{pmatrix} \right) \begin{pmatrix} U_k^{(1)} \\ U_k^{(2)} \\ U_k^{(3)} \end{pmatrix}.$$

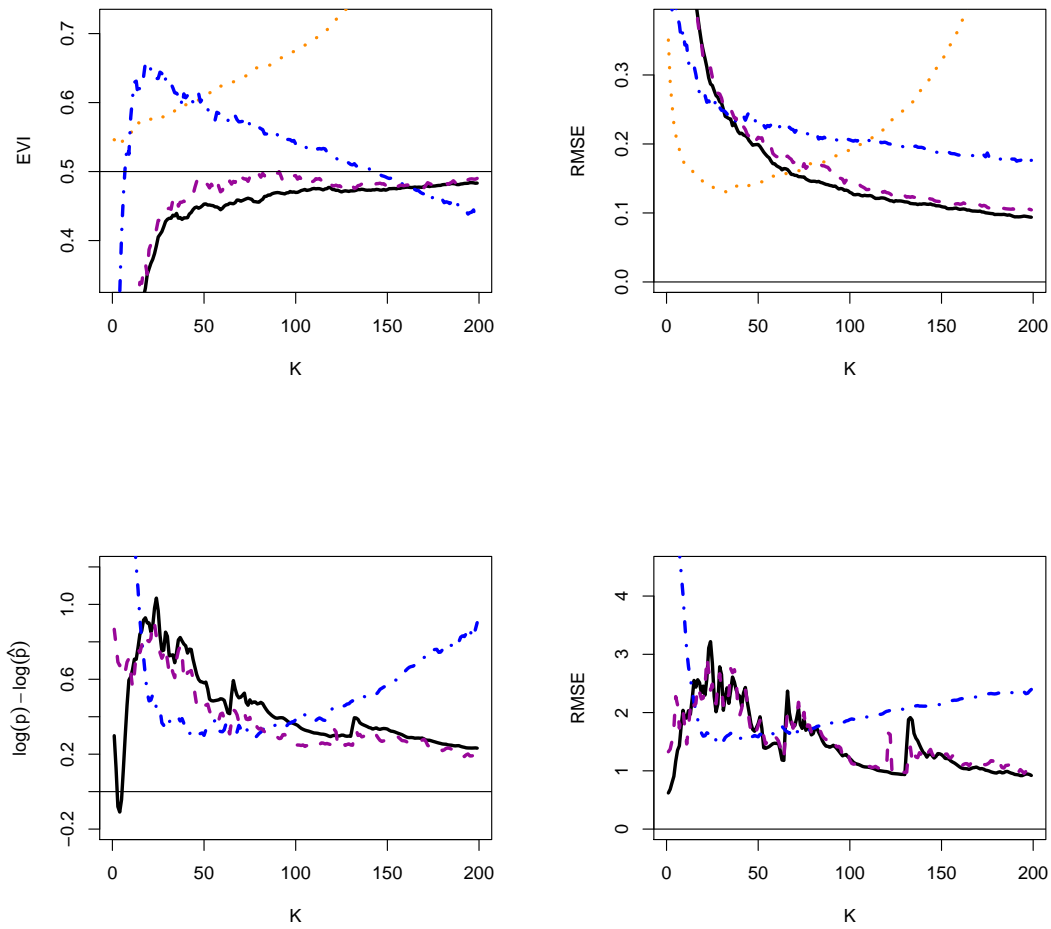


Figure 1: Burr distribution with $\xi = 0.5$ and $\rho = -0.5$. Estimation of ξ (top) and tail probability (bottom) using minimum variance principle, bias (left), RMSE (right): GPD-ML (full line), $E\hat{p}$ (dash-dotted), $E\bar{p}$ (dashed) and ridge regression estimator (dotted).

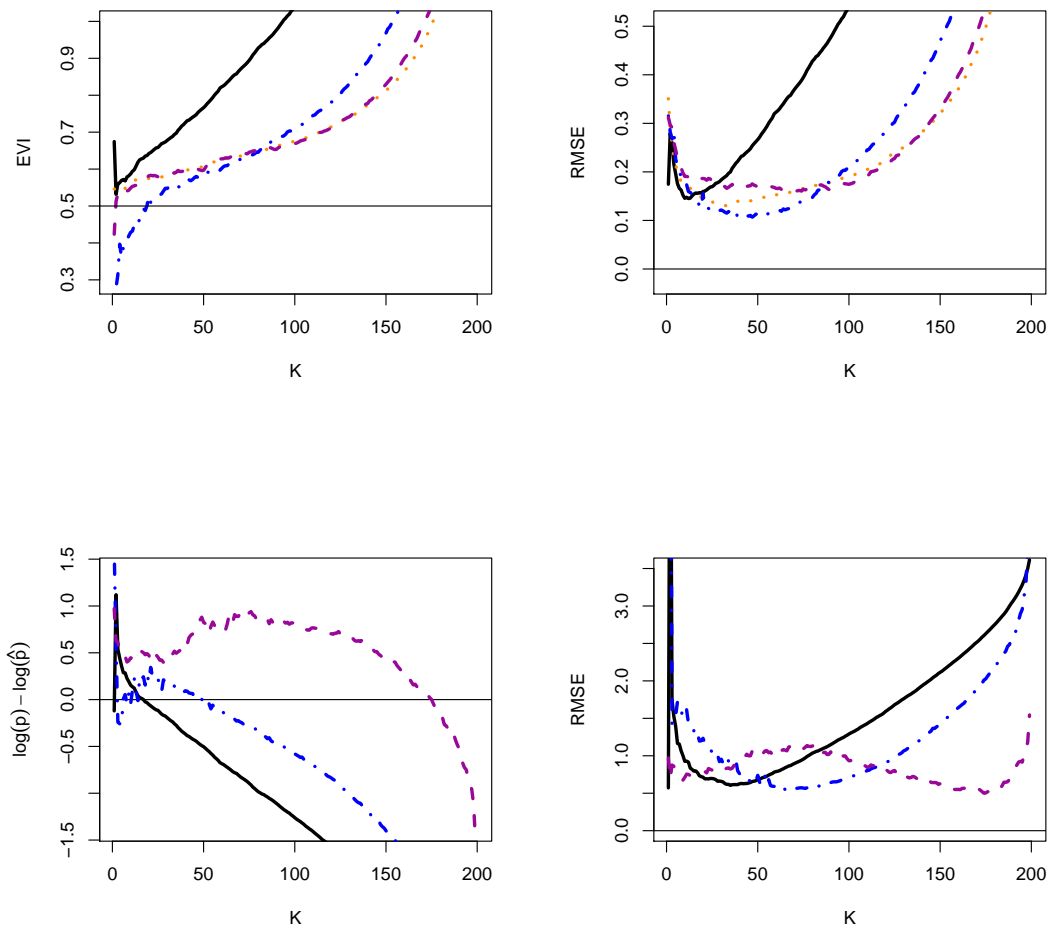


Figure 2: Burr distribution with $\xi = 0.5$ and $\rho = -0.5$. Estimation of ξ (top) and tail probability (bottom) using minimum variance principle, bias (left), RMSE (right): Pareto-ML (full line), Ep^+ (dash-dotted), $E\bar{p}^+$ (dashed) and corrected Hill estimator (dotted).

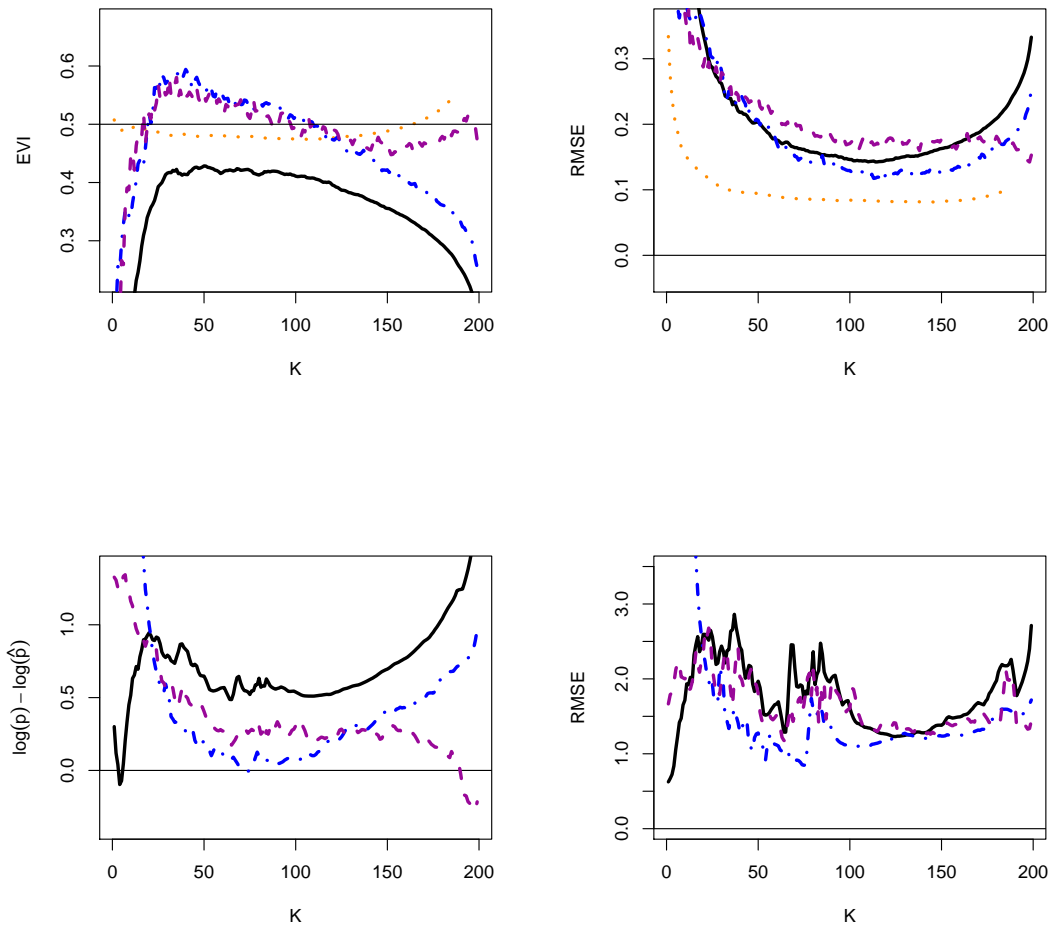


Figure 3: Fréchet distribution with $\xi = 0.5$. Estimation of ξ (top) and tail probability (bottom), bias (left), RMSE (right): GPD-ML (full line), $E\rho$ with $\rho = -2$ (dash-dotted), $E\bar{\rho}$ with $(k_*, m) = (190, 150)$ (dashed), and ridge regression estimator (dotted).

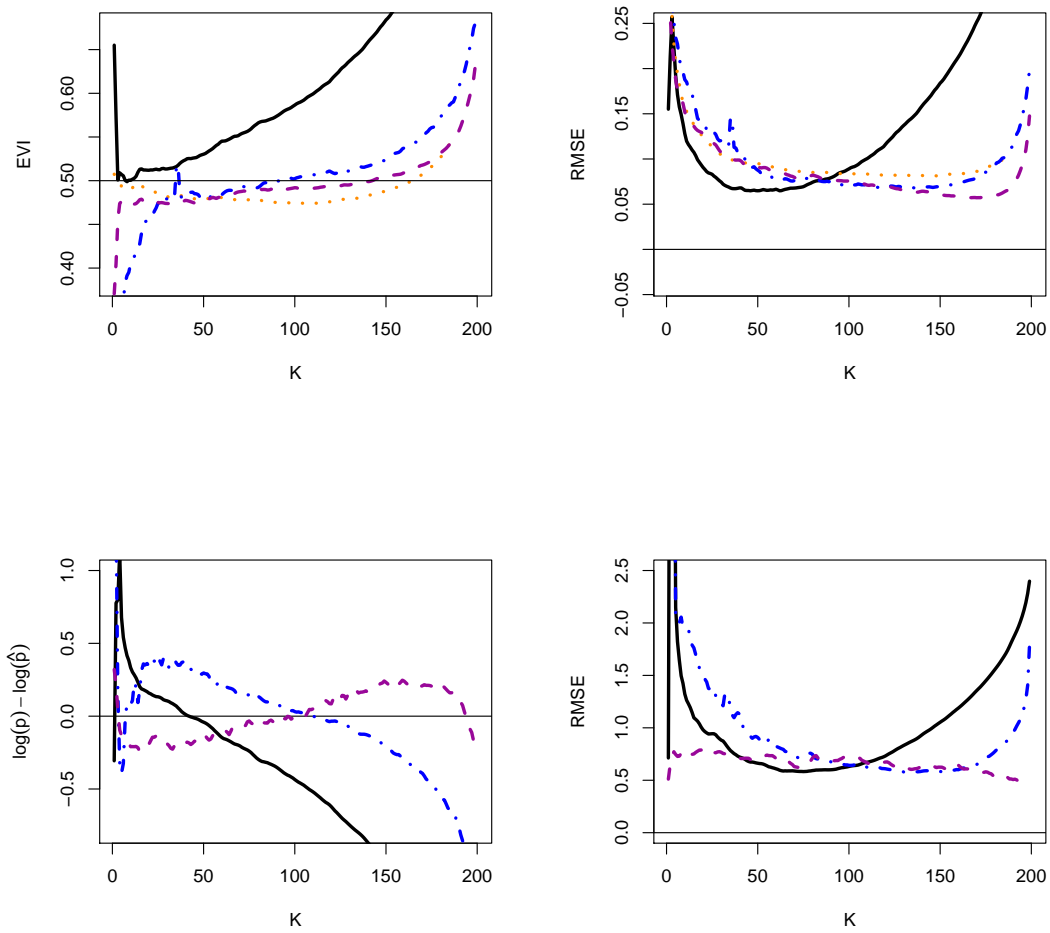


Figure 4: Fréchet distribution with $\xi = 0.5$. Estimation of ξ (top) and tail probability (bottom) using minimum variance principle, bias (left), RMSE (right): Pareto-ML (full line), $E\hat{p}^+$ (dash-dotted), $E\bar{p}^+$ (dashed) and corrected Hill estimator (dotted).

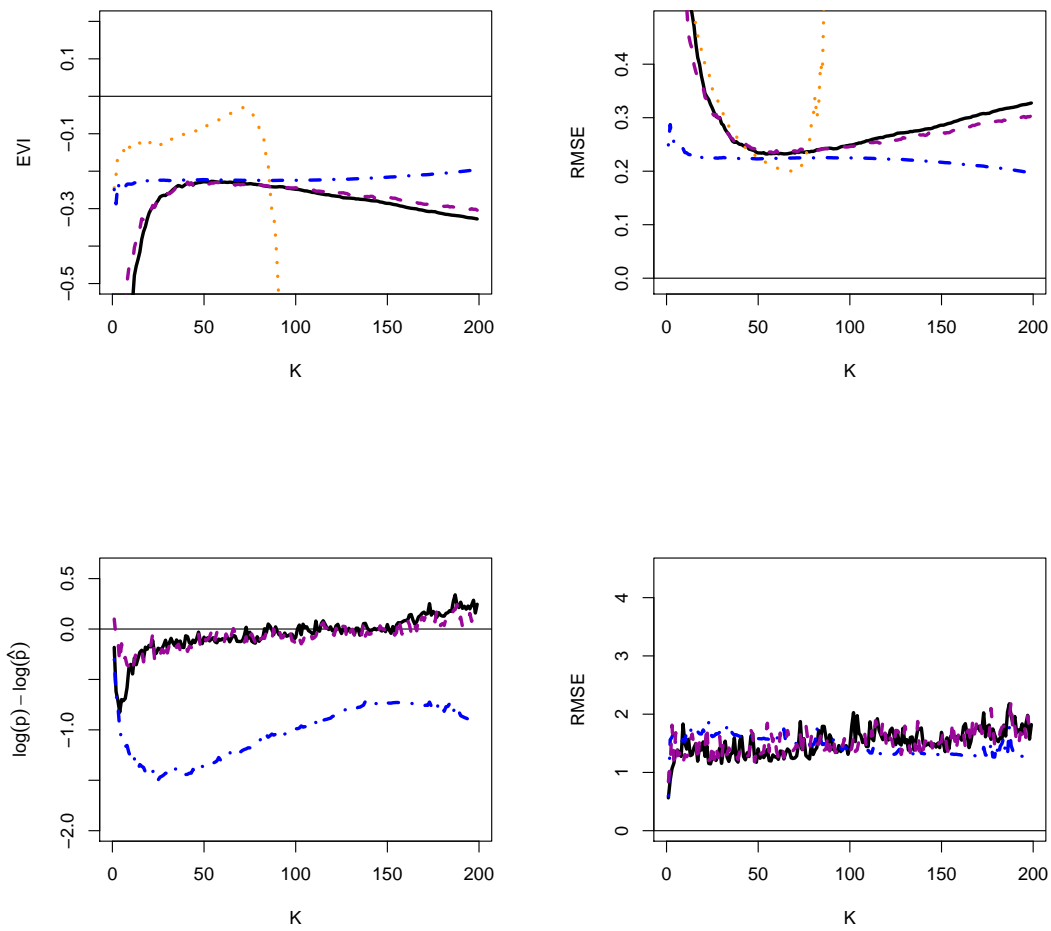


Figure 5: Standard normal distribution ($\xi = 0$ and $\tilde{\rho} = 0$). Estimation of ξ (top) and tail probability (bottom) using minimum variance principle, bias (left), RMSE (right): GPD-ML (full line), $E\hat{p}$ (dash-dotted), $E\bar{p}$ (dashed) and ridge regression estimator (dotted).

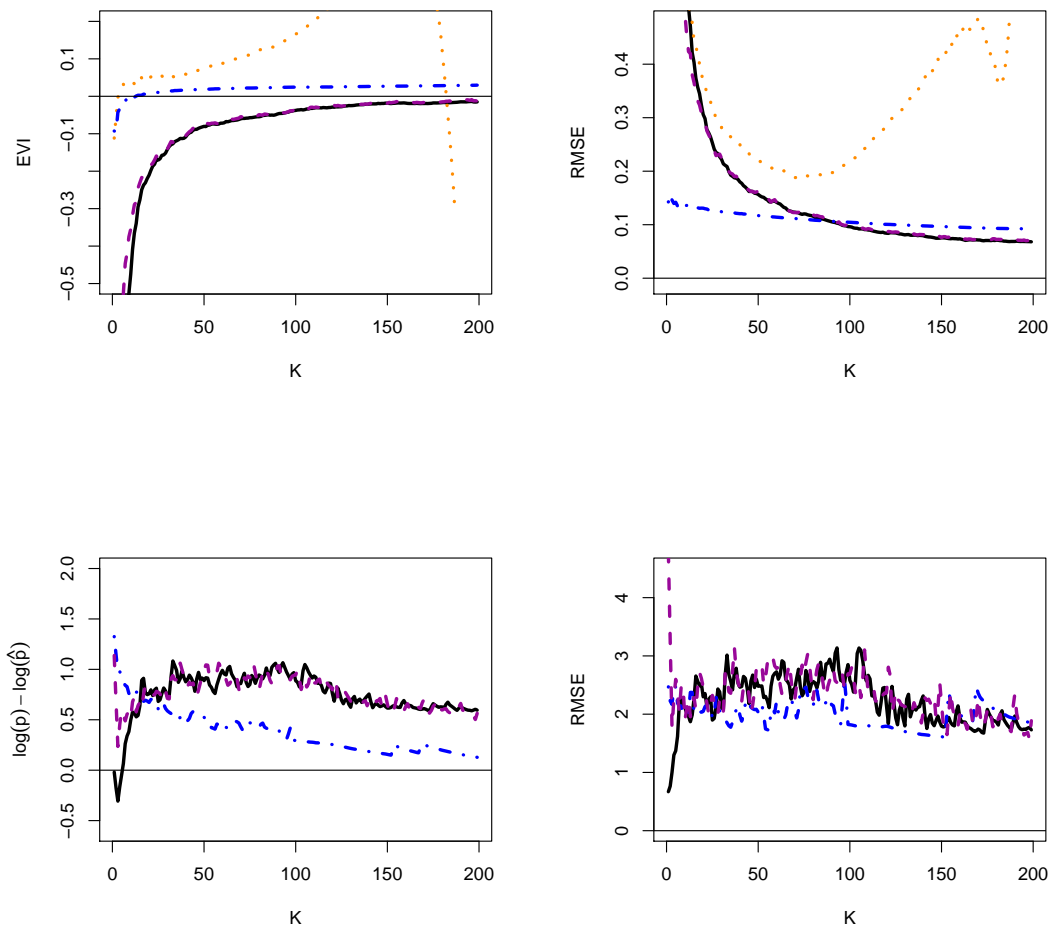


Figure 6: The exponential distribution ($\xi = 0$ and $\tilde{\rho} = 0$). Estimation of ξ (top) and tail probability (bottom) using minimum variance principle, bias (left), RMSE (right): GPD-ML (full line), $E\hat{p}$ (dash-dotted), $E\bar{p}$ (dashed) and ridge regression estimator (dotted).

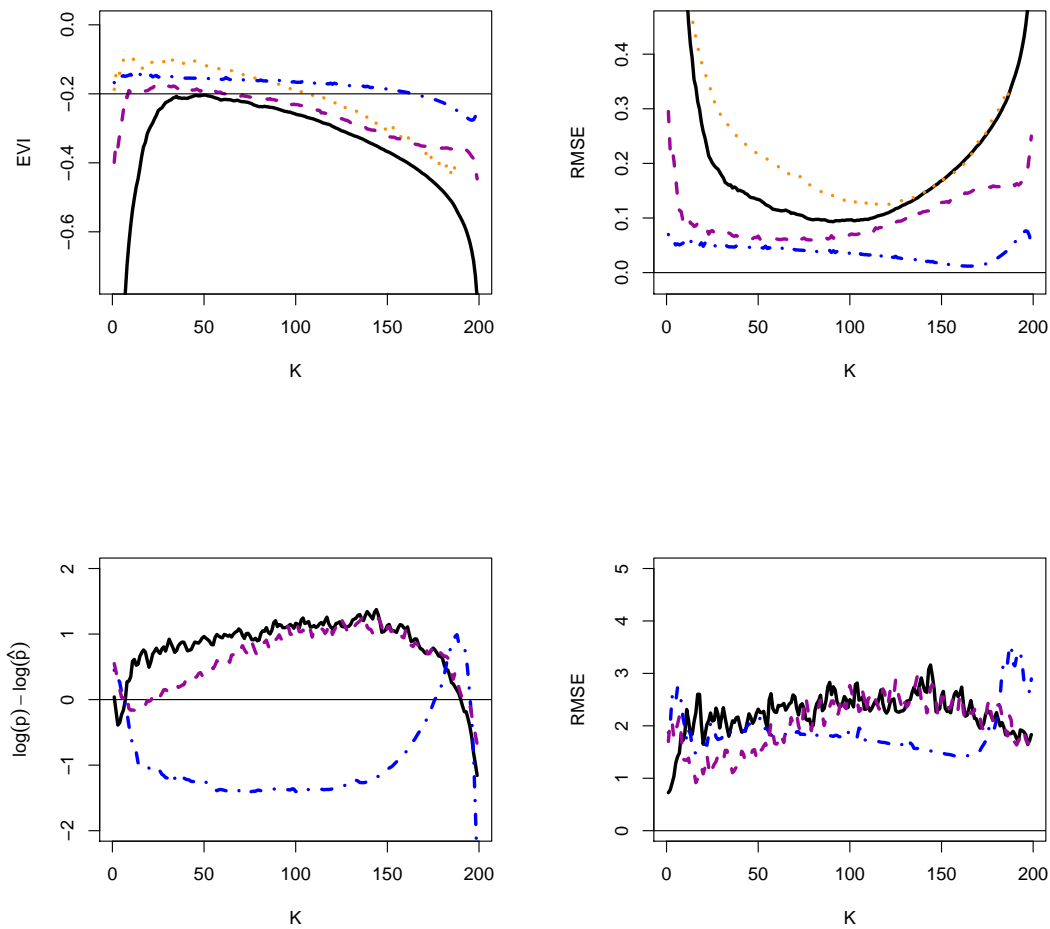


Figure 7: Reversed Burr distribution ($\xi = -0.2$ and $\tilde{\rho} = -1$). Estimation of ξ (top) and tail probability (bottom) using minimum variance principle, bias (left), RMSE (right): GPD-ML (full line), $E\hat{p}$ (dash-dotted), $E\bar{p}$ (dashed) and ridge regression estimator (dotted).

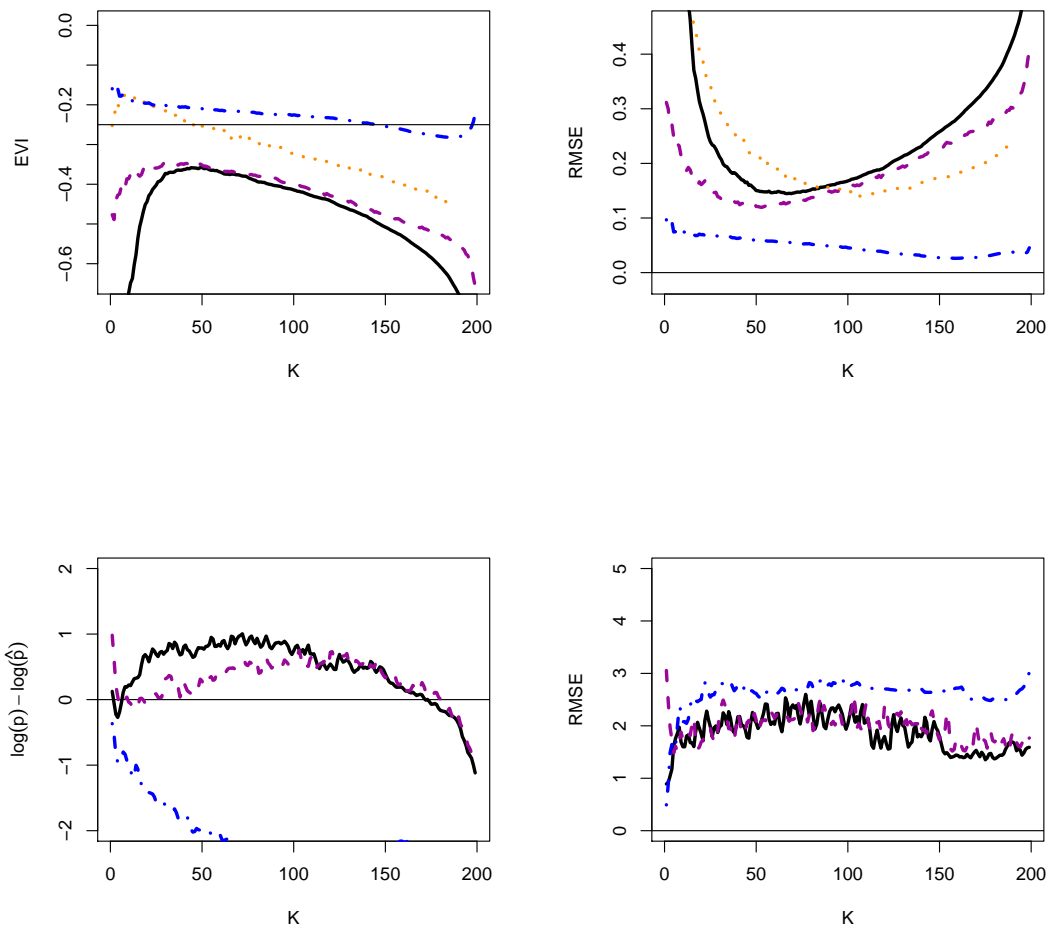


Figure 8: Extreme value Weibull distribution ($\xi = -0.25$ and $\tilde{\rho} = -1$). Estimation of ξ (top) and tail probability (bottom) using minimum variance principle, bias (left), RMSE (right): GPD-ML (full line), $E\hat{p}$ (dash-dotted), $E\bar{p}$ (dashed) and ridge regression estimator (dotted).

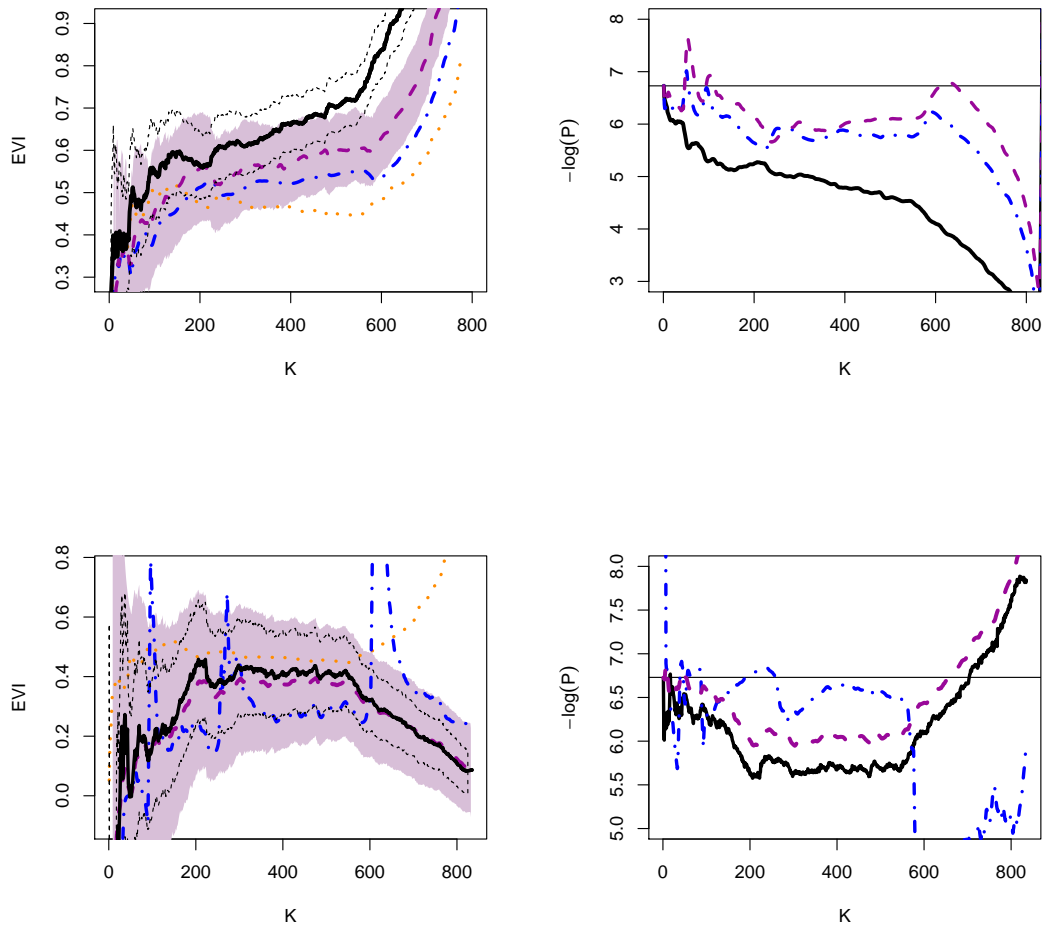


Figure 9: Ultimates of Belgian car insurance claims: estimation of ξ with asymptotic confidence intervals (left), tail probability estimation at maximum observation (right), Pareto-based analysis (top) and GPD-based analysis (bottom): classical ML estimation (full line with dotted confidence intervals), E_p (dashed with shaded confidence intervals) and $E_{\bar{p}}$ (dash-dotted). CH (top left) and ridge regression (bottom left) estimators are indicated by dotted lines.

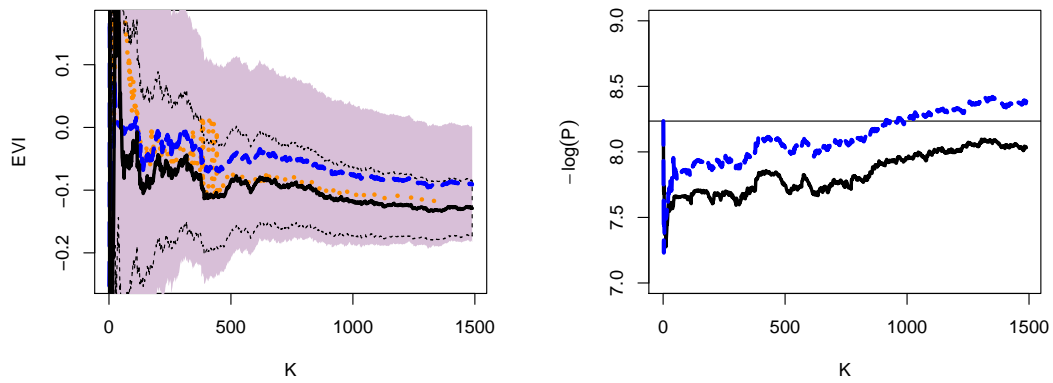


Figure 10: Lifetime data from the Netherlands, female persons who died in 1986. Left: estimation of ξ with asymptotic confidence intervals for classical ML estimation (full line with dotted confidence intervals), E_p (dashed with shaded confidence intervals, $\tilde{\rho} = -0.5$) and ridge regression (dotted). Right: tail probability estimation at maximum observation for classical ML estimation (full line) and E_p (dashed).